



PIT - CUNY - NEW YORK - USA

OPTIMIZATION OF PHOTON-SAIL TRAJECTORIES TO ALPHA CENTAURI USING EVOLUTIONARY NEUROCONTROL

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Content

- Introduction
- Alpha Centauri
- Photon Sail
- Mission Analysis
- Trajectory Optimization
- Results
- Conclusion



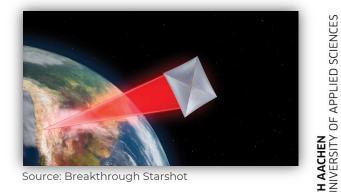
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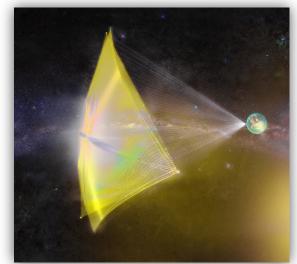


Introduction

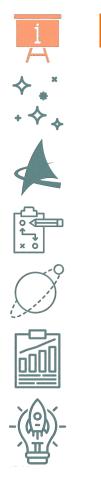
Breakthrough Starshot



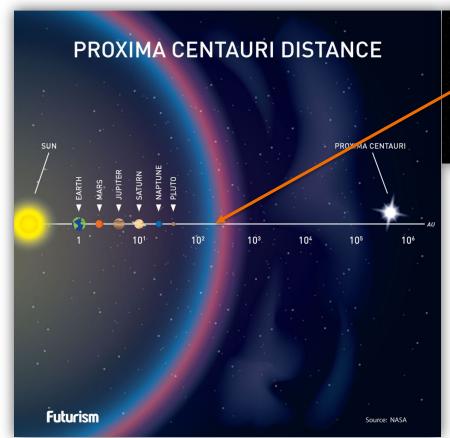
- Prove interstellar travel to Proxima Centauri
- Laser-driven sail
- 20% of speed of light → 20 years
- Fly-through mission → 1 day passage
- Goal: Pictures of exoplanet Proxima b

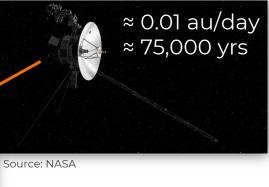


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Introduction





Breakthrough Starshot:

Solar system escape velocity \approx 35 au/day

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Introduction

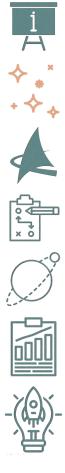
Primary Goal

To find the optimal steering strategy for a photonic sail to get **captured** into the Alpha-Centauri system after a minimum-time transfer from Earth

Secondary Goal



To investigate transfer trajectories between the Alpha-Centauri stars and **orbit-raising** maneuvers to explore the habitable zones of the stars



Alpha Centauri

 $\approx 275~000$ au from the Sun

Why?

Earth-like exoplanet Proxima b in the habitable zone of $\alpha\mbox{-}Cen\mbox{ C}$

Sun

4.36 light years = 275,732 au

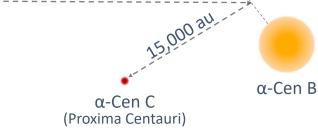


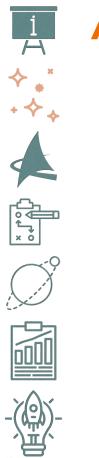
Source: NASA/ESA/Hubble

α-Cen A

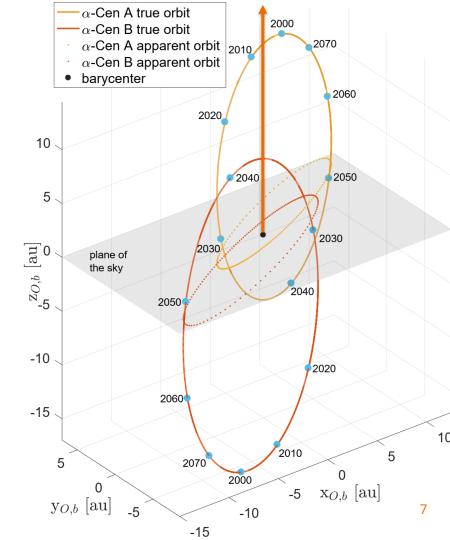


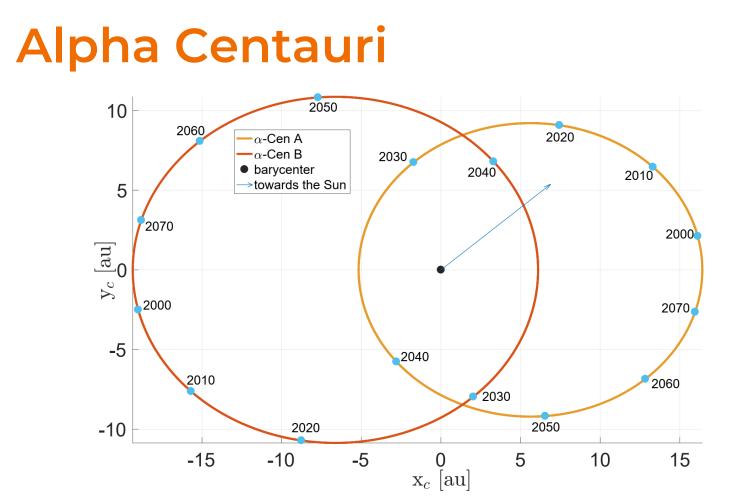
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Alpha Centauri





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Photon Sail

Continuous, but small acceleration

Generate thrust without propellant

Lightness number β = performance parameter:

SRP-acceleration Gravitational acceleration





Lightness number	Sun	α-Cen A	α-Cen B
β	1.0	1.374	0.534

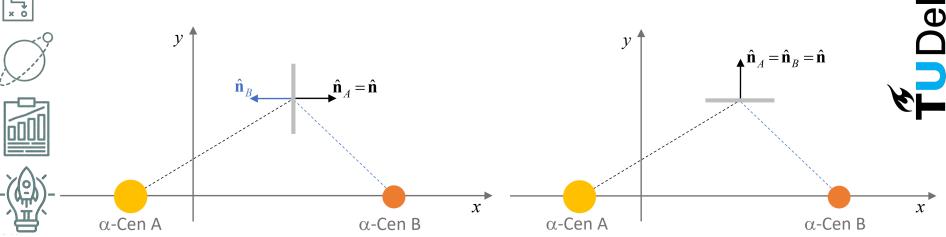
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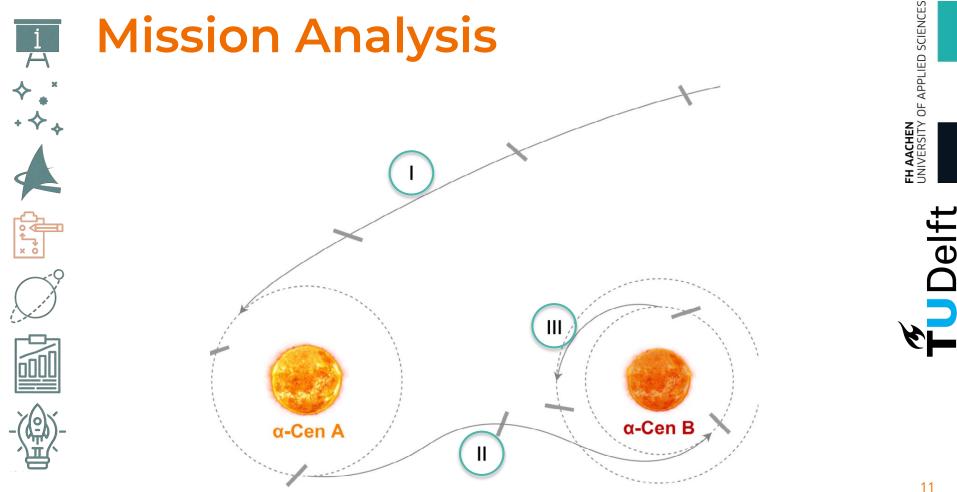
Photon Sail

Photon-sail dynamics under effect of *two* radiative sources (photon-pressure augmented elliptical restricted three body problem)

Acceleration depends on sail orientation and configuration



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Trajectory Optimization Find optimal steering strategy: $f(t) = \int_{0}^{t} \delta_{i}$



Minimise transfer time



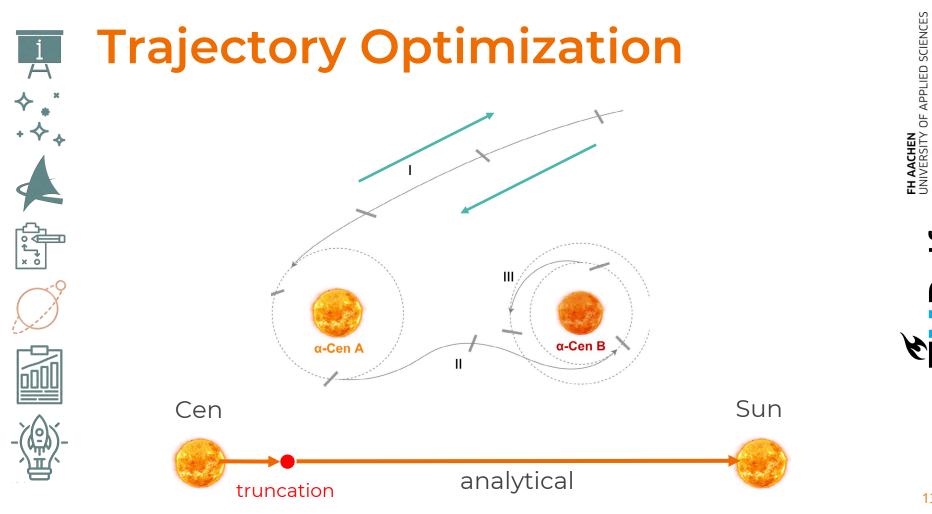


• Initial condition: circular orbit about star

 $\mathbf{u}(t) = [\alpha(t), \ \delta(t)]^T$

- Propagate forwards in time until escape conditions
- Reversing orbital motion of star system

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Trajectory Optimization

Global low-thrust trajectory optimization software

Optimal control solver: InTrance



Machine-learning approach combining neural networks and evolutionary algorithms



Advantages: mission description can be very broad and no initial quess is required

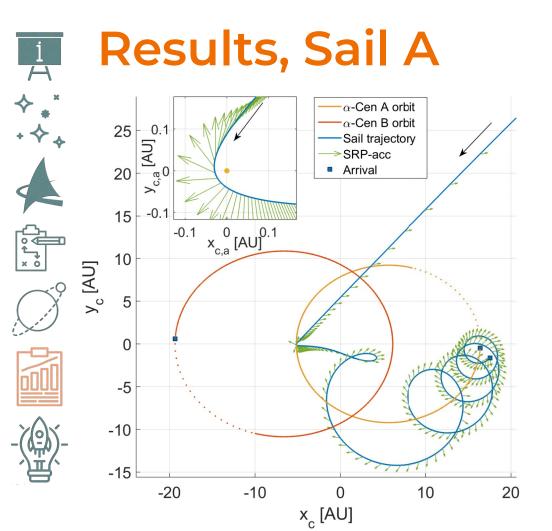


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	Sail	β	Material	Sail Loading [g/m²]	FH AACHEN UNIVERSITY
	(A)	0.040	Kapton	37	_
	В	0.765	Gold foil	2.0	elt
	C	4.370	Composite graphene-based	0.35	
		1779	Graphene	0.00086	K

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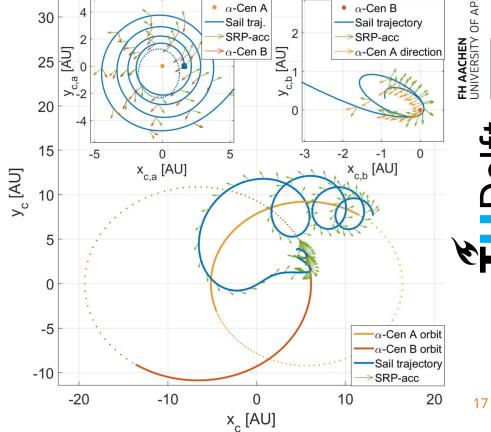
Travel time: 18,790 yrs Injection speed: 0.023% c





Results, Sail A

Transfer time: 24 yrs



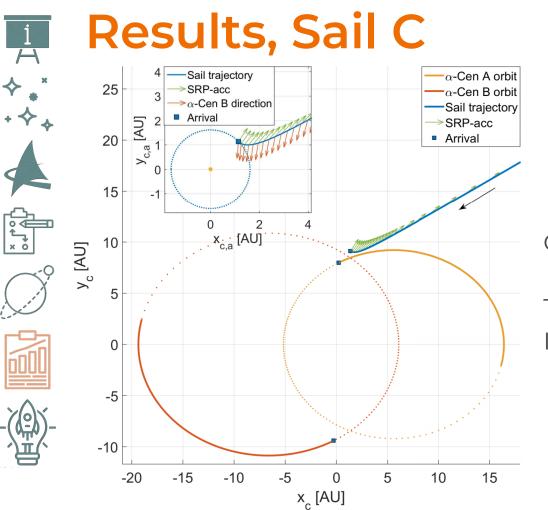
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One-sided reflective sail

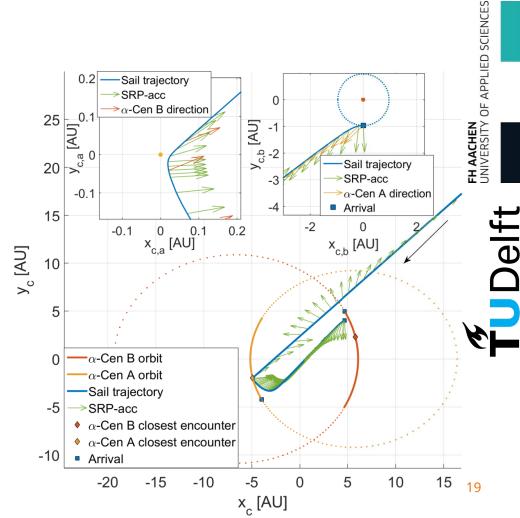
Travel time: 16,372 yrs Injection speed: 0.026% c

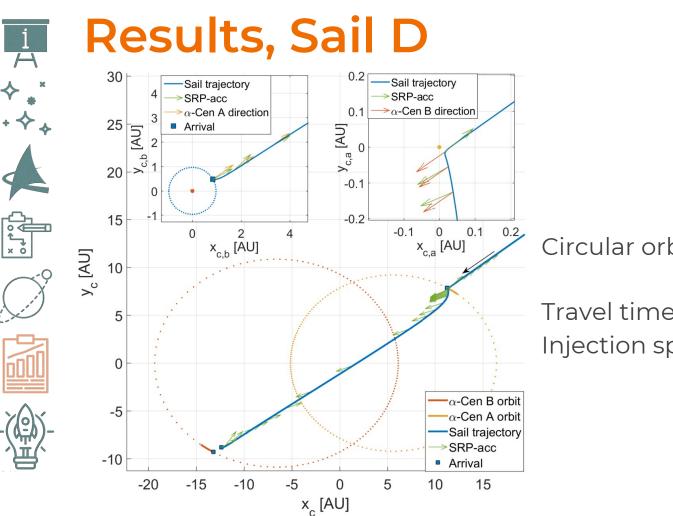


Results, Sail C

Two-sided reflective sail

Travel time: 2,000 yrs Injection speed: 0.23% c





Circular orbit

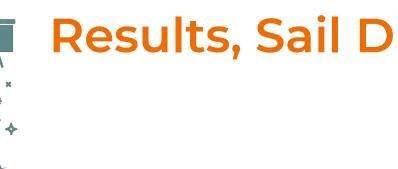
Travel time: 111 yrs Injection speed: 3.9% c



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21



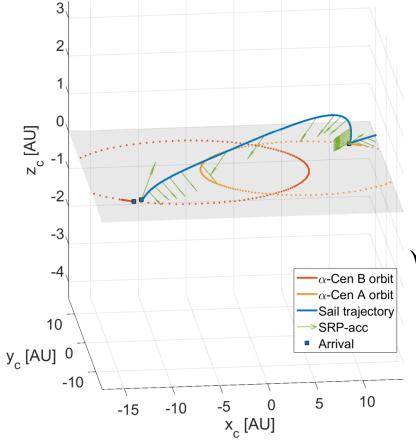
Highly-eccentric orbit

Injection speed: 5.5% c

Travel time: 77.6 yrs

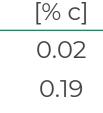






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Summary

Sail

А

B

	[% c]	[yrs]	[yrs]	[yrs]
	0.02	18,790	23.8	3.0
	0.19	2,293	5.4	1.0
(1-sided)	0.03	16,372	18.3	2.7
(2-sided)	0.23	1,950	2.3	1.8
	3.90	111	0.3	n.a.
(e=0.9)	5.50	77.6	n.a.	n.a.

Injection speed Capture Transfer Orbit raising



Average improvement of capture trajectories of 30% in terms of interstellar flight time compared to previous work

22



Conclusion

- Sending a sail today vs. more advanced photonic sail in the future Ι.
- 2. Capturing of sail according to Breakthrough Starshot would take 2,000 years instead of 20 years



3. Futuristic ultralight sail enables capture in less than 80 years, suggesting to jettison the sail upon arrival





- Travel time from Sun to Alpha Centauri for two-sided reflective sail is 4. eight times shorter than one-sided reflective sail
- 5. Technological development required for two-sided sails
- 6. Fly-through mission is probably the only option for a first mission to Alpha Centauri

Thank you for your attention



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